# Separation for the stationary Prandtl equation 

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## Outline

Introduction

Behaviour near separation: heuristics and formal results

Main result and ideas

Sketch of proof

Conclusion and perspectives

## Plan

## Introduction

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## What is boundary layer separation?

Flow with low viscosity around an obstacle, in the presence of an adverse pressure gradient (=the outer flow is decreasing along the obstacle):


Figure: Cross-section of a flow past a cylinder (source: ONERA, France)

After separation: widely open problem (turbulence?) Mathematical interest: understand the vanishing viscosity limit in the Navier-Stokes equation.
Industrial interest: reduce drag.

## Derivation of the (stationary) Prandtl system

Starting point: stationary 2d Navier-Stokes with small viscosity $\nu \ll 1$ in a half-plane. Velocity field $\mathbf{u}^{\nu}: \mathbf{R}_{+}^{2} \rightarrow \mathbf{R}^{2}$ with

$$
\begin{align*}
\left(\mathbf{u}^{\nu} \cdot \nabla\right) \mathbf{u}^{\nu}+\nabla p^{\nu}-\nu \Delta \mathbf{u}^{\nu} & =\mathbf{f} \text { in } \mathbf{R}_{+}^{2} \\
\operatorname{div} \mathbf{u}^{\nu} & =0 \text { in } \mathbf{R}_{+}^{2}  \tag{1}\\
& \mathbf{u}_{\mid y=0}^{\nu}=0
\end{align*}
$$



Stationary Prandtll system: with $Y=y / \sqrt{\nu}$,


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Ansatz: $\mathbf{u}^{\nu}(x, y) \simeq\left\{\begin{array}{l}\mathbf{u}^{E}(x, y) \text { for } y \gg \sqrt{\nu} \text { (sol. of 2d Euler), } \\ \left(u\left(x, \frac{y}{\sqrt{\nu}}\right), \sqrt{\nu} v\left(x, \frac{y}{\sqrt{\nu}}\right)\right) \text { for } y \lesssim \sqrt{\nu} .\end{array}\right.$

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Stationary Prandtl system: with $Y=y / \sqrt{\nu}$,

$$
\begin{array}{r}
u \partial_{x} u+v \partial_{Y} u-\partial_{Y Y} u=f_{1}(x, 0)-\frac{\partial p^{E}(x, 0)}{\partial x} \\
\partial_{x} u+\partial_{Y} v=0 \\
u_{\mid Y=0}=0, \quad v_{Y=0}=0, \quad \lim _{Y \rightarrow \infty} u=u^{E}(x, 0)
\end{array}
$$

## The stationary Prandtl equation: general existence result

## Stationary Prandtl system:

$$
\begin{array}{r}
u \partial_{X} u+v \partial_{Y} u-\partial_{Y Y} u=g(x) \\
\partial_{X} u+\partial_{Y} v=0, \quad u_{\mid x=0}=u_{0}  \tag{P}\\
u_{\mid Y=0}=0, \quad v_{Y}=0=0, \quad \lim _{Y \rightarrow \infty} u=u^{E}(x, 0)
\end{array}
$$

$\sim$ Nonlocal, scalar evolution eq. in $x$.
Locally well-posed as long as $u>0$ :
Theorem [Oleinik, 1962]: Let $u_{0} \in \mathcal{C}_{b}^{2, \alpha}\left(\mathbf{R}_{+}\right), \alpha>0$. Assume that $u_{0}(Y)>0$ for $Y>0, u_{0}^{\prime}(0)>0$, and that

$$
\partial r y u_{0}+g(0)=O\left(Y^{2}\right) \text { for } 0<Y \ll 1
$$

Then there exists $x^{*}>0$ such that $(P)$ has a unique strong $\mathcal{C}^{2}$ solution in $\left\{(x, Y) \in \mathbf{R}^{2}, 0 \leq x<x^{*}, 0 \leq Y\right\}$. If $g(x) \geq 0$, then

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Then there exists $x^{*}>0$ such that $(P)$ has a unique strong $\mathcal{C}^{2}$ solution in $\left\{(x, Y) \in \mathbf{R}^{2}, 0 \leq x<x^{*}, 0 \leq Y\right\}$. If $g(x) \geq 0$, then $x^{*}=+\infty$.

## The stationary Prandtl equation: monotonicity, comparison principle

Nonlinear change of variables [von Mises]: transforms ( P ) into a local diffusion equation (porous medium type).
$\rightarrow$ Maximum principle holds for the new eq. by standard tools and arguments.

- Monotonicity is preserved by (P).
- Comparison principle for the Prandtl equation:
- Consider a super-solution $\bar{u}$ for Prandtl;
- Von Mises $\rightsquigarrow$ sub/super solution $\bar{w}$ for the eq. in new variables;
- Maximum principle for the new eq.: $w \leq \bar{w}$.
- ODE arguments: $u \leq \bar{u}$.

Remark: we will consider strictly increasing solutions only: ensures that separation happens at the boundary.

## General mechanism behind separation

Setting: monotone solutions with adverse pressure gradient $(g \leq 0)$.


In general there exists $x^{*}$ such that

$$
\frac{\partial u}{\partial Y}_{\mid x=x^{*}, Y=0}=0
$$

For $x>x^{*}, Y \lesssim 1, u$ takes negative values: reversed flow near the boundary.
$\rightarrow$ There exists a curve $Y=F(x)$ such that $u(x, F(x))=0$ :
separation of the boundary layer.
Definition: $x^{*}$ is called the separation point.

## Questions

1. Does separation really happen? Can you cook-up solutions of $(P)$ such that $\partial_{Y} u_{\mid Y=0}(x) \rightarrow 0$ as $x \rightarrow x^{*}$ for some finite $x^{*}$ ?
2. If you can, what is the rate at which $\partial_{Y} u_{\mid Y=0}(x)$ vanishes?

## Related results

Instability results (time dependent version):
Local well-posedness in high regularity spaces (analytic, Gevrey) [Sammartino\& Caflisch; Gérard-Varet\& Masmoudi...] or for monotonic data [Oleinik; Masmoudi\&Wong; Alexandre, Wang, Xu\& Yang...]
BUT instabilities develop in short time in Sobolev spaces [Grenier; Gérard-Varet\&Dormy...]

Formation of singularities (time dependent version): [Kukavica, Vicol, Wang](van Dommelen-Shen singularity)
Starting from real analytic initial data, for specific outer Euler flow, some solutions display singularities in finite time.

Justification of the Prandtl Ansatz when $\nu \ll 1$ : [Guo\& Nguyen, lyer] Starting from stationary Navier-Stokes above a moving plate (non-zero boundary condition on the wall), local convergence/global convergence for small data ( $\rightarrow$ no singularity).

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## Formal derivations of the self similar rate

- Formal computations of an exact solution to $(P)$ by [Goldstein '48, Stewartson '58] thanks to Taylor expansions in self-similar variables.
Self similar change of variables: rely on the observation that $(P)$ is invariant by the scaling

$$
\begin{aligned}
& u(x, Y) \rightarrow \frac{1}{\sqrt{\mu}} u\left(\mu x, \mu^{1 / 4} Y\right), \quad \text { with } \mu>0 . \\
& v(x, y) \rightarrow \mu^{1 / 4} v\left(\mu x, \mu^{1 / 4} Y\right),
\end{aligned}
$$

Remark: the coefficients of the asymptotic expansion are never entirely determined (dependence on initial data?)

- Heuristic argument by Landau: $\partial_{Y} u_{\mid Y=0}(x) \sim \sqrt{x^{*}-x}$. (same as Goldstein\& Stewartson.)


## Statement by Luis Caffarelli and Weinan E

In a paper published in 2000, Weinan E announces a joint result with Luis Caffarelli, stating:
Theorem [Caffarelli, E, 1995]: Assume that $g(x)=-1$, and that $u_{0}$ satisfies

$$
u_{0}^{2}-\frac{3}{2} \partial_{Y} u_{0} \int_{0}^{Y} u_{0} \geq 0
$$

Then:

- There exists $x^{*}>0$ such that the solution cannot be extended beyond $x^{*}$;
- The family $u_{\mu}:=\frac{1}{\sqrt{\mu}} u\left(\mu\left(x^{*}-x\right), \mu^{1 / 4} Y\right)$ is compact in $\mathcal{C}\left(\mathbf{R}_{+}^{2}\right)$.
The author also states two (non-trivial...) Lemmas playing a key role in the proof, relying on the maximum principle.
Unfortunately the complete proof was never published.. Goal of the present talk: propose an alternate proof, relying on different techniques, and giving a more quantitative result


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## Main result

Theorem [D., Masmoudi, '16]:
Consider the equation (P) with $g(x)=-1$. Then for a class of initial data $u_{0}=u_{\mid x=0}$ satisfying

- $u_{0}$ is strictly increasing with respect to $Y$;
- $u_{0}(Y) \simeq \lambda_{0} Y+\frac{Y^{2}}{2}$ for $Y \ll 1$ and for some $\lambda_{0} \ll 1$; separation occurs at a finite distance $x^{*}=O\left(\lambda_{0}^{2}\right)$.
Moreover for all $x \in\left(0, x^{*}\right)$,
and for some weight $w=w(x, Y)$,
where for $Y \lesssim\left(x^{*}-x\right)^{1 / 4}$



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Moreover for all $x \in\left(0, x^{*}\right)$,

$$
\lambda(x):=\partial_{Y} u_{\mid Y=0}(x) \sim C \sqrt{x^{*}-x}
$$

and for some weight $w=w(x, Y)$,

$$
\left\|u-u^{a p p}\right\|_{L^{2}(w)}=o\left(\left\|u^{a p p}\right\|_{L^{2}(w)}\right) \text { as } x \rightarrow x^{*}
$$

where for $Y \lesssim\left(x^{*}-x\right)^{1 / 4}$

$$
u^{a p p}(x, Y)=\lambda(x) Y+\frac{Y^{2}}{2}-\alpha Y^{4}-\beta \lambda(x)^{-1} Y^{7}
$$

## Remarks

- Two results: asymptotic behavior of $\partial_{Y} u_{\mid Y=0}$ and error estimate between $u$ and $u^{a p p}$.
- The self-similar rate is the one predicted by Landau, Goldstein and Stewartson.
- Existence of other (unstable) rates?
- Encompasses their result;
- More stringent assumptions;
- Quantitative result; the limit is identified
- Tools and scheme of proof:
- Inspired by study of blow-up rates for NLS [Zakharov, Sulem\&

Sulem; Merle\& Raphaël]; successfully applied to wave and
Schrödinger maps, Keller-Segel system, harmonic heat flow [Merle, Raphaël, Rodnianski, Schweyer..

- Perform a self-similar change of variables; approximate
solution, energy estimates in rescaled variables;
- Use techniques based on modulation of variables to find the self-similar rate $\lambda(x)=\partial_{Y} u_{Y}=0$


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- Use techniques based on modulation of variables to find the self-similar rate $\lambda(x)=\partial_{Y} u_{\mid Y=0}$.


## The self-similar change of variables

Let $\lambda(x):=\partial_{Y} u_{Y=0}(x)$. Define $\tilde{u}=\tilde{u}(x, \xi)$ by

$$
\tilde{u}(x, \xi)=\lambda^{-2}(x) u(x, \lambda(x) \xi) .
$$

Then

$$
\lambda^{4}\left(\tilde{u}_{u} \tilde{u}_{x}-\tilde{u}_{\xi} \int_{0}^{\xi} \tilde{u}_{x}\right)+\lambda_{x} \lambda^{3}\left(2 \tilde{u}^{2}-3 \tilde{u}_{\xi} \int_{0}^{\xi} \tilde{u}\right)-\tilde{u}_{\xi \xi}=-1 .
$$

Define $s, b, U$ such that

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Define $s, b, U$ such that

$$
b=-2 \lambda_{x} \lambda^{3}, \quad \frac{d x}{d s}=\lambda^{4}, \quad U(s, \xi)=\tilde{u}(x(s), \xi)
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Then $U$ satisfies

$$
\begin{equation*}
U U_{s}-U_{\xi} \int_{0}^{\xi} U_{s}-b U^{2}+\frac{3 b}{2} U_{\xi} \int_{0}^{\xi} U-U_{\xi \xi}=-1 . \tag{R}
\end{equation*}
$$

Remark: $x \rightarrow x^{*}$ corresponds to $s \rightarrow \infty$ provided $\int_{0}^{x^{*}} \lambda^{-4}=\infty$.

## Strategy

From now on, work only on equation on $U$ :

$$
U U_{s}-U_{\xi} \int_{0}^{\xi} U_{s}-b U^{2}+\frac{3 b}{2} U_{\xi} \int_{0}^{\xi} U-U_{\xi \xi}=-1
$$

$\triangle$ At this stage, $b$ is an unknown. The asymptotic behavior of $b$ dictates the self-similar rate $\lambda(x)$. Scheme of proof:

1. Construct an approximate solution;
2. Choose the approximate solution with the "least possible growth" at infinity: heuristics for the modulation rate $b$;
3. Energy estimate on the remainder of the solution.

Rule of thumb: the expected rate $\lambda(x)=C \sqrt{x^{*}-x}$ corresponds to

$$
b(s)=\frac{1}{s} \Leftrightarrow b_{s}+b^{2}=0 .
$$

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Sketch of proof

## Conclusion and perspectives

## Introduction

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The approximate solution
Energy estimates

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## Construction of an approximate solution

$$
\underbrace{U U_{s}-U_{\xi} \int_{0}^{\xi} U_{s}-b U^{2}+\frac{3 b}{2} U_{\xi} \int_{0}^{\xi} U}_{=: \mathcal{A}(U)}-U_{\xi \xi}=-1 .
$$

Boundary conditions at $\xi=0$ : by definition of $\lambda$,

$$
U_{\mid \xi=0}=0, \partial_{\xi} U_{\mid \xi=0}=1
$$

Case $b=0$ : exact stationary solution

$$
U_{0}:=\xi+\frac{\xi^{2}}{2}(\sim \text { "ground state" }) .
$$

Case $b \neq 0$ : Look for asymptotic expansion in the form

$$
U=U_{0}+b T_{1}+b^{2} T_{2}+\cdots
$$

Then $T_{1}$ is given by $b \partial_{\xi \xi} T_{1}=\mathcal{A}\left(U_{0}\right)+1 \Rightarrow T_{1}=-\frac{\xi^{4}}{48}$. What about $T_{2}$ ?

## Finding the ODE on $b$

Rule: choice of the approx. solution with the least possible growth.
Remainder for $U_{1}:=U_{0}+b T_{1}$ :

$$
\begin{aligned}
& \mathcal{A}\left(U_{1}\right)-\partial_{\xi \xi} U_{1}+1 \\
= & -\alpha\left(\frac{4}{5} b_{s}+\frac{13}{10} b^{2}\right) \xi^{5}-\frac{3}{10} \alpha\left(b_{s}+b^{2}\right) \xi^{6}+\alpha^{2} \frac{b}{5}\left(b_{s}+b^{2}\right) \xi^{8} .
\end{aligned}
$$

"Choice" of $b$ such that the $\xi^{6}$ term disappears:

$$
b_{s}+b^{2}=0
$$

## Ansatz: in the algorithm defining $T_{N}$, replace every occurrence of Consequence: setting $U_{N}:=U_{0}+b T_{1}+\cdots+b^{N} T_{N}$, <br> $\square$ <br> 

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Consequence: setting $U_{N}:=U_{0}+b T_{1}+\cdots+b^{N} T_{N}$,
$U-U_{2} \sim\left(b_{s}+b^{2}\right)\left(c_{7} \xi^{7}+c_{8} \xi^{8}\right)$ near $\xi=0$.
$\Rightarrow\left\|U-U_{N}\right\| \gtrsim\left|b_{s}+b^{2}\right|$ for $N \geq 2$.

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## Obtaining stability estimates

General idea: control $\left(b_{s}+b^{2}\right)^{2}$ via an appropriate energy $E(s):=\left\|U-U_{N}\right\|^{2}$.
Goal: prove that

$$
\begin{equation*}
E(s)=O\left(s^{-4-\eta}\right) \text { for some } \eta>0 . \tag{2}
\end{equation*}
$$

Starting point: write eq. on $U-U_{N}$ for $N$ "large" $(N=3)$.
$\rightarrow$ of the form

$$
\partial_{s}\left(U-U_{N}\right)+\cdots=\text { remainder terms. }
$$

Error estimate: prove that

$$
\frac{d E}{d s}+\frac{\alpha}{s} E(s) \leq \rho(s) .
$$

In order to achieve (2), one needs:

- $\rho(s)=O\left(s^{-5-\eta}\right)$ : "good" approximate solution;
- $\alpha>$ 4: algebraic manipulations on the equation (R).


## A transport-diffusion equation for $U$

Define, for $W \in L^{\infty}\left(\mathbf{R}_{+}\right)$,

$$
L_{U} W:=U W-U_{\xi} \int_{0}^{\xi} W=\left(\frac{\int_{0}^{\xi} W}{U}\right)_{\xi} U^{2}
$$

so that, if $W(\xi)=O\left(\xi^{2}\right)$ near $\xi=0$,

$$
L_{U}^{-1} W=\left(U \int_{0}^{\xi} \frac{W}{U^{2}}\right)_{\xi}
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Remark: $L_{U}^{-1} \sim$ division by $U \simeq \xi+\xi^{2} / 2$.

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$$

Define $\mathcal{L}_{U}:=L_{U}^{-1} \partial_{\xi \xi}$ : diffusion operator. Then, with $V=U-U_{N}$

$$
\partial_{s} V-b V+\frac{b}{2} \xi \partial_{\xi} V-\mathcal{L}_{U} V=\mathcal{R}_{N}
$$

## Energy and dissipation terms

$$
V=U-U_{N}, \quad \partial_{s} V-b V+\frac{b}{2} \xi \partial_{\xi} V-\mathcal{L}_{U} V=\mathcal{R}_{N}
$$

## Facts:

1. Estimates are "almost" linear (up so some commutators...)
2. $V=U-U_{N} \sim\left(b_{s}+b^{2}\right)\left(c_{1} \xi^{7}+c_{2} \xi^{8}\right)$ for $\xi \ll 1$;
3. $\mathcal{L}_{U}$ is a diffusion operator $\left(\mathcal{L}_{U} \sim \frac{1}{U} \partial_{\xi \xi}\right)$.

Ideas:

- Differentiate equation/use weights/apply operator $\mathcal{L}_{U}$ to make the zero-order + transport term positive:

$$
\partial_{\xi}^{k}\left(\partial_{s} V-b V+\frac{b}{2} \xi \partial_{\xi} V\right)=\left(\partial_{s}+\frac{k-2}{2} b+\frac{b}{2} \xi \partial_{\xi}\right) \partial_{\xi}^{k} V .
$$

- Compromise between control of $\left(b_{s}+b^{2}\right)^{2}$ by energy/small remainder term/positivity of transport and diffusion.
$\square$


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- Compromise between control of $\left(b_{s}+b^{2}\right)^{2}$ by energy/small remainder term/positivity of transport and diffusion...
- Energy $E(s):=\left\|\left(\mathcal{L}_{U}^{2} V\right)_{\xi}\right\|_{H^{1}(w)}^{2}$ for some weight $w$.


## Tools for the proof

- Weighted $L^{2}$ estimates;
- Commutator estimates;
- $L^{\infty}$ estimates coming from maximum principle (sub-super solutions);
- Bootstrap argument.


## Plan

## Introduction

Behaviour near separation: heuristics and formal results

Main result and ideas

Sketch of proof

Conclusion and perspectives

## Summary

- Proof of separation for the stationary Prandtl equation in the case of adverse pressure gradient $(g(x)=-1)$;
- Computation of a self-similar rate compatible with Landau's predictions:

$$
\partial_{Y} u_{Y=0} \sim \sqrt{x^{*}-x}
$$

- Quantitative error estimates between true solution and approximate solution (in weighted $H^{s}$ spaces);
- Construction of an approximate solution, ODE on the separation rate: relies on arguments close to singularity formation for the nonlinear Schrödinger equation.
- Energy estimates rely heavily on the structure of the equation, and need to be combined with maximum principle techniques.


## Perspectives

- Other (unstable) separation rates?
- Better description of the solution in the zone $Y \gtrsim\left(x^{*}-x\right)^{1 / 4}$ ( $\Leftrightarrow \xi \gtrsim s^{1 / 4}$ );
- Higher dimensions?
- What happens after separation?

1. Both turbulent and laminar regimes are possible... But $^{\text {B }}$ turbulent regimes are out of reach for the time being.
2. $\triangle$ The validity of the Prandtl system after separation is far from clear...

Thank you for your attention!

